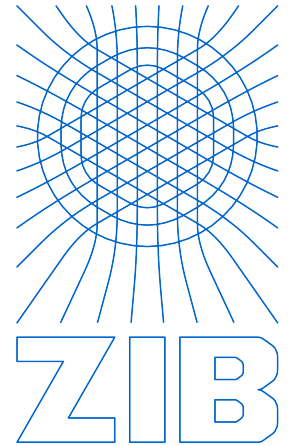


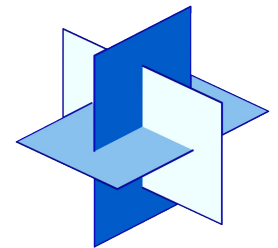
Workshop Kaskade 7 & Applications

Prerequisites: C++ Knowledge

M. Weiser, L. Lubkoll



Zuse Institute
Berlin



MATHEON

C++ in a nutshell

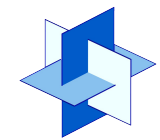
- syntax
- classes
- overloading
- templates

Standard library

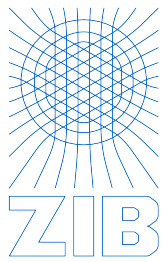
- containers
- algorithms
- IO

Template metaprogramming

- rationale
- metaprogramming concepts
- boost::fusion



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C++ in a Nutshell

What is C++?

Taxonomy

- imperative
- procedural
- object-oriented
- generic
- functional



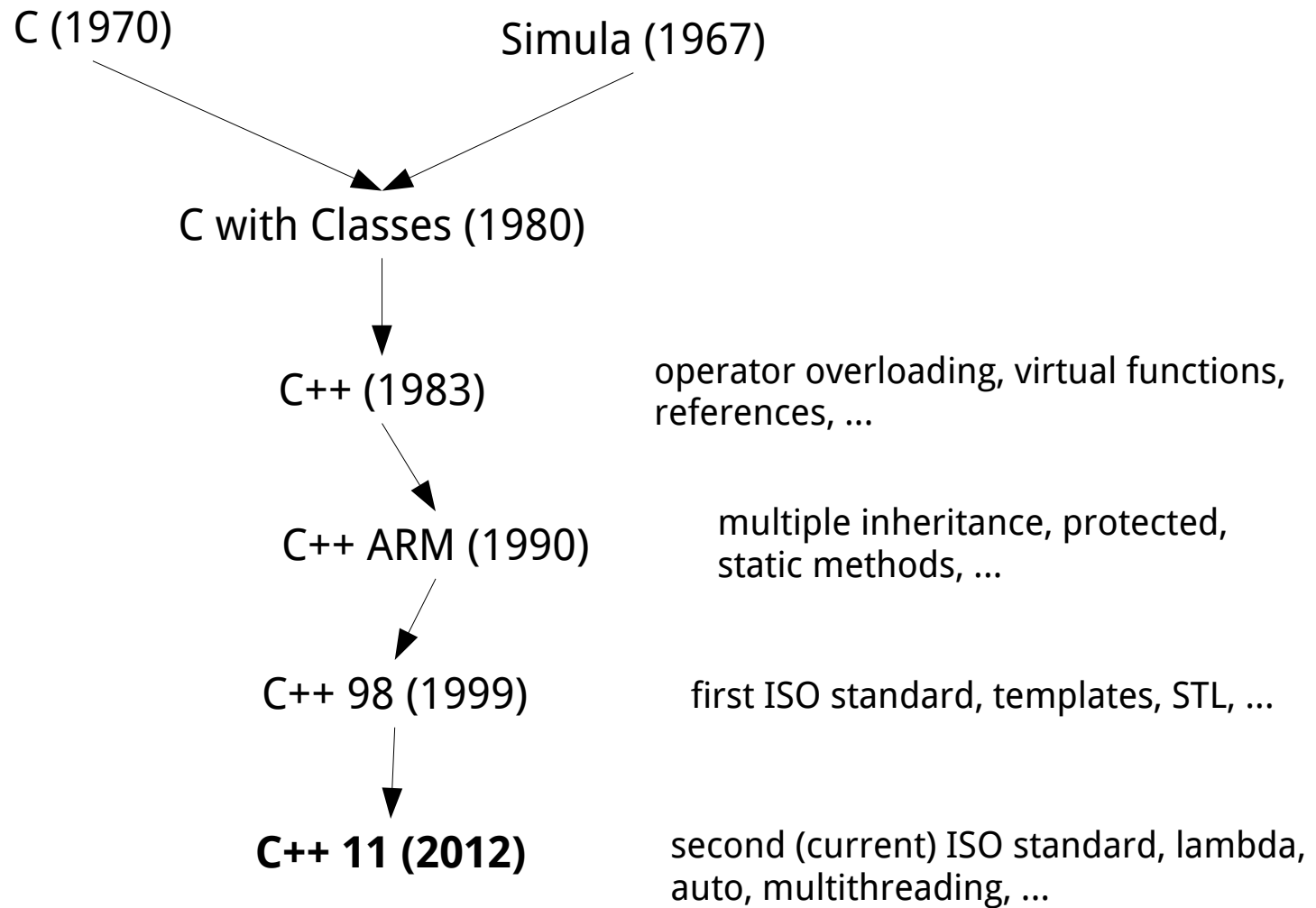
multi-paradigm language

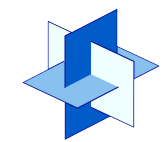
Design philosophy

- systems programming
- allow high efficiency
- provide abstractions

“In C++ it's harder to shoot yourself in the foot,
but when you do, you blow off your whole leg.”

- Bjarne Stroustrup -





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Teach Yourself C++ in 21 Days

Days 1 - 10
Teach yourself variables, constants, arrays, strings, expressions, statements, functions,...



Days 11 - 21
**Teach yourself program flow,
pointers, references, classes,
objects, inheritance, polymor-
phism,**



Days 22 - 697

Do a lot of recreational programming. Have fun hacking but remember to learn from your mistakes.



Days 698 - 3648
Interact with other programmers.
Work on programming projects
together. Learn from them.



Days 3649 - 7781
Teach yourself advanced theoretical physics and formulate a consistent theory of quantum gravity.



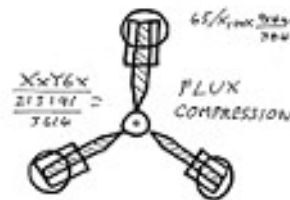
Days 7782 - 14611
**Teach yourself biochemistry,
molecular biology, genetics,...**



Day 14611
Use knowledge of biology to
make an age-reversing potion.



Day 14611
Use knowledge of physics to
build flux capacitor and go back
in time to day 21.



Day 21
Replace younger self.



„As far as I know, this is the easiest way to *Teach Yourself C++ in 21 days*“
(The Abstruse Goose, abstrusegoose.com/249)

Available

Built-in types, Functions, Classes

Built-in types

int, unsigned int, double, char, ...

```
int a;  
a = 42;  
int b = 42;  
char c = 'x';
```

// declaration (value of „a“ undefined!)
// initialization
// better both at same time

Declare read-only variable (const)

```
int const d1 = 42;  
const int d1 = a;
```

// must be initialized in declaration
// same as above

Declare compile-time constant (constexpr)

can be understood by the compiler

```
constexpr int e = 42;
```


Syntax

- **if:** if(condition) statement

?: condition ? statement(condition=true) : statement(condition=false)

```
if(a==1) {  
    a = 2;  
}
```

```
if(a==1) std::cout << "Ankara" << std::endl;  
else {  
    a -= 1;  
    std::cout << "Berlin" << std::endl;  
}
```

```
std::cout << "computation " <<  
(solver.failed() ? "failed" : "successful") << std::endl;
```

- **while:** while(condition) statement

```
while(a<1000) { b = b+1; }
```

Syntax

- for a) for(initialization; condition; increase) statement
b) for(element : range) statement
c) std::for_each (see STL: Algorithms)

```
std::vector<double> vec = { 1.0, 2.0, 3.0};  
  
for(int i=0; i<vec.size(); ++i)  
    std::cout << vec[i] << std::endl;  
  
for(auto iter = vec.begin(); iter!=vec.end(); ++iter)  
    std::cout << *iter << std::endl;  
  
for(double const e : vec) std::cout << e << std::endl;
```

```
double addDoubles(double a, double b);           // declaration (in .cpp-file)

double addDoubles(double a, double b) {           // definition (in .hh-file)
    return a+b;
}

void printHello() {                               // declaration + definition
    std::cout << "Hello Ankara" << std::endl;
}

constexpr int addInts(int a, int b) {             // function that can be
    return a+b;                                   // evaluated during compilation
}                                                  // if a and b are compile-time constants

typedef std::array<int, addInts(20,22)> MyIntArray;

int main() {
    double c = addDoubles(2.0,3.5);
    while(true) printHello();                     // infinite loop :)
}
```

(L-value) References '&'

- stores address of variable with longer lifetime than reference
- useful for large objects: avoids copying
- assignment & initialization in same place

```
int& b = a;  
int const& c = b;  
a = 1;  
b = 2;  
c = 3;
```

```
// b contains the address of a  
// c contains the address of a and is fixed  
// c = b = a = 1  
// c = a = b = 2  
// error: can not assign to const&
```

- **Danger:** Referenced object may go out of scope! **RESPONSIBILITY OF PROGRAMMER!**
- Using large objects?
i.e. a function that writes a grid to a file

```
void writeGrid(Grid grid, std::string filename);
```

unnecessary copy of grid (rel. big, >> 1 MB)

(L-value) References '&'

- stores address of variable with longer lifetime than reference
- useful for large objects: avoids copying
- assignment & initialization in same place

```
int& b = a;  
int const& c = b;  
a = 1;  
b = 2;  
c = 3;
```

```
// b contains the address of a  
// c contains the address of a and is fixed  
// c = b = a = 1  
// c = a = b = 2  
// error: can not assign to const&
```

- **Danger:** Referenced object may go out of scope!
- Using large objects?
i.e. a function that writes a grid to a file

better

```
void writeGrid(Grid const& grid, std::string filename);
```

no copy, can take temporaries

see <http://herbsutter.com/2008/01/01/gotw-88-a-candidate-for-the-most-important-const/>

What to do with functions that return big objects?

```
BigObject bigObject0() { return BigObject(); }  
std::unique_ptr<BigObject> bigObject1() {  
    return std::unique_ptr<BigObject>(new BigObject());  
}  
BigObject& bigObject2() { return BigObject(); }  
  
BigObject obj0 = bigObject0();  
std::unique_ptr<BigObject> obj1( bigObject1() );  
BigObject obj2 = bigObject2();
```

What to do with functions that return big objects?

```
BigObject bigObject0() { return BigObject(); }  
std::unique_ptr<BigObject> bigObject1() {  
    return std::unique_ptr<BigObject>(new BigObject());  
}  
BigObject& bigObject2() { return BigObject(); }  
  
BigObject obj0 = bigObject0();  
std::unique_ptr<BigObject> obj1( bigObject1() );  
BigObject obj2 = bigObject2();
```

create object,
copy to stack,
copy to obj0
=> 2 copies

create pointer to object
(object created on heap)
=> copy only pointer
(cheap)

create reference to object, copy address to stack,
delete object, obj2 tries to call the constructor with
the deleted object => segmentation fault

What to do with functions that return big objects?

```
BigObject bigObject0() { return BigObject(); }  
std::unique_ptr<BigObject> bigObject1() {  
    return std::unique_ptr<BigObject>(new BigObject());  
}  
BigObject& bigObject2() { return BigObject(); }  
  
BigObject obj0 = bigObject0();  
std::unique_ptr<BigObject> obj1( bigObject1() );  
BigObject obj2 = bigObject2();
```

never return
(l-value) references
to temporary
objects

most
inefficient

ugly syntax

stupid,
referenced object
directly goes out of scope

create object,
copy to stack,
copy to obj0
=> 2 copies

create pointer to object
(object created on heap)
=> copy only pointer
(cheap)

create reference to object, copy address to stack,
delete object, obj2 tries to call the constructor with
the deleted object => segmentation fault

Scope & Lifetime

- variables "die" at end of scope (i.g. with '}')
- the scope of return values ends after the line containing the function call ends

```
int getOne() { return 1; }

int main(){
    int a = 1;

    for(int i=0; i<42; ++i)
    {
        a = b;
        int& b = a;
        int& c = getOne();
        int d = c;
        int const& e = getOne();

        int f = a;
    }
}
```

// 1 does not have an address in memory!

// compile time error: b undefined

// b contains the address of a.

// c contains the address of the temporary result of getOne()

// => undefined value of c => SEGMENTATION FAULT

// const& extends the lifetime of temporaries to the lifetime of the reference

// no problem with copies, but expensive for big objects.

// b - f are deleted.

// a is deleted.

R-value references ('&&')

- can only appear on right-hand side of an assignment ('=')
- can not have a name
- do not have to be in a meaningful state **at end of scope**
- admit move-semantics & perfect forwarding

Move semantics: instead of copy move data from one object to another

```
class BigObject { ...  
    BigObject(BigObject&& bigObject);           // move constructor  
    ...  
};  
  
BigObject bigObject3() { return BigObject(); }
```

efficient & elegant syntax `BigObject obj4 = bigObject3();` // create object, copy address, move data

Perfect forwarding: [search via startpage.com](http://startpage.com)

- use types as parameters, i.e. instead of

c-style container

implement specific container for each type and array size

```
class c_array_int_3
{
public:
    c_array_int_3(int a, int b, int c){
        data[0] = a; data[1] = b; data[2] = c;
    }

    int& operator[](size_t i) {
        return data[i];
    }

private:
    int[3] data;
};

c_array_int_3 myArray(1,2,3);
```

we can write

templated c++-style container

one implementation for "all" types and sizes

```
template <class Data, int n>
class array {
public:
    array() {
        for(int i=0; i<n; ++i) data[i]=0;
    }

    Data& operator[](size_t i) {
        return data[i];
    }

private:
    Data[n] data;
};

array<int,3> myArray;
```

Note:
templates, as well as
all template member
functions, must be
defined in header-files

- are used to structure code
- allow the use of functions and classes with same signature in different namespaces
- here the most important namespaces are `std`, `boost::fusion`, `Dune` and `Kaskade`

same functions in same namespace

```
void printHello() {  
    std::cout << "Hello Ankara" << std::endl;  
}
```

```
void printHello() {  
    std::cout << "Hello Berlin" << std::endl;  
}
```

// same name and arguments => on function call
// compiler does not know which
// printHello-function is meant

vector class in namespace 'std'

```
template <class Type, class Allocator=std::allocator<Type> >  
class vector;
```

vector class in namespace 'boost::fusion'

```
template <typename T0=unspecified, typename T1=unspecified, ... ,  
          typename TN=unspecified>  
class vector;
```

Raw pointers ('*', see abstrusegoose.com/483 „bad boy“)

a contains address, ***a** contains value

Danger of memory leaks and segmentation faults

```
int* a = new int(5);  
*a = *a + 1;  
a = a + 1;  
delete a;
```

// a contains the value 6
// a points to the next entry in memory
// remove allocated storage

Use raw pointers for pointing issues only

```
struct PersonalTrainer { ...  
  
    void setTrainedPerson(Person& person_) {  
        person = &person_;  
    }  
  
private:  
    Person* person;  
};
```

// big person => copy is expensive
// use & to access address

Rule of thumb: - **NEVER USE "NEW" WITHOUT MATCHING "DELETE"!**
- **NEVER USE "NEW", USE SMART POINTERS INSTEAD!**

Smart pointers

- similar to references, but may point to different objects
- initialization without assignment possible (nullptr)

use `std::unique_ptr` if only one pointer should point to an object

```
#include<memory> // std::unique_ptr
#include <utilitiy> // std::move

std::unique_ptr<int> p(new int(5)); // resp. p(std::make_unique<int>(5))
std::unique_ptr<int> p0(p); // compile time error: no constructor
std::unique_ptr<int> p1(std::move(p)); // makes p an r-value reference
// => p contains null pointer (nullptr)
std::unique_ptr<int> p2(p1.get()); // shared unique_ptr => double free error
std::unique_ptr<int> p3(p1.release()); // ok, p1 releases pointer
int d = *p3; // d = 5
```

Smart pointers

- similar to references, but may point to different objects
- initialization without assignment possible (nullptr)

use `std::shared_ptr` if multiple pointers should point to an object

```
#include<memory>                                // std::shared_ptr

std::shared_ptr<int> p(std::make_shared(5)) ;
std::shared_ptr<int> p1(p) ;                      // ok for shared pointers
std::shared_ptr<int> p2(p1.get()) ;               // pointers don't know about each other
                                                    // => double free error
int d = *p1;                                       // d = 5
```


Double Free Error

*** glibc detected *** test3: free(): invalid pointer: 0x0804c01c ***

===== Backtrace: =====

/lib/libc.so.6(+0x6ff0b)[0xb7526f0b]

/usr/lib/libstdc++.so.6(_ZdlPv+0x1f)[0xb771eb2f]

test3[0x8048cc8]

test3[0x804891d]

/lib/libc.so.6(__libc_start_main+0xf3)[0xb74d0003]

test3[0x80489d1]

===== Memory map: =====

08048000-0804a000 r-xp 00000000 08:03 4068942 /home/lars/ZIB/workspace/test3/Release/test3

0804a000-0804b000 r--p 00001000 08:03 4068942 /home/lars/ZIB/workspace/test3/Release/test3

0804b000-0804c000 rw-p 00002000 08:03 4068942 /home/lars/ZIB/workspace/test3/Release/test3

0804c000-0806d000 rw-p 00000000 00:00 0 [heap]

b74b4000-b74b7000 rw-p 00000000 00:00 0

b74b7000-b761e000 r-xp 00000000 08:01 917844 /lib/libc-2.14.1.so

b761e000-b7620000 r--p 00167000 08:01 917844 /lib/libc-2.14.1.so

b7620000-b7621000 rw-p 00169000 08:01 917844 /lib/libc-2.14.1.so

b7621000-b7624000 rw-p 00000000 00:00 0

b7624000-b7640000 r-xp 00000000 08:01 917846 /lib/libgcc_s.so.1

b7640000-b7641000 r--p 0001b000 08:01 917846 /lib/libgcc_s.so.1

b7641000-b7642000 rw-p 0001c000 08:01 917846 /lib/libgcc_s.so.1

b7642000-b766b000 r-xp 00000000 08:01 921827 /lib/libm-2.14.1.so

b766b000-b766c000 r--p 00028000 08:01 921827 /lib/libm-2.14.1.so

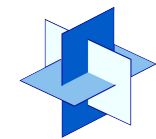
b766c000-b766d000 rw-p 00029000 08:01 921827 /lib/libm-2.14.1.so

possible reason:
smart pointer to an object
that gets destroyed by
some other source

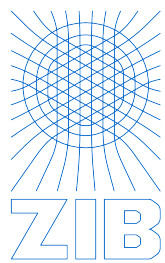
Double Free Error

```
b766d000-b774f000 r-xp 00000000 08:01 1189091 /usr/lib/libstdc++.so.6.0.16
b774f000-b7753000 r--p 000e2000 08:01 1189091 /usr/lib/libstdc++.so.6.0.16
b7753000-b7754000 rw-p 000e6000 08:01 1189091 /usr/lib/libstdc++.so.6.0.16
b7754000-b775b000 rw-p 00000000 00:00 0
b777c000-b777f000 rw-p 00000000 00:00 0
b777f000-b779e000 r-xp 00000000 08:01 917515 /lib/ld-2.14.1.so
b779e000-b779f000 r--p 0001f000 08:01 917515 /lib/ld-2.14.1.so
b779f000-b77a0000 rw-p 00020000 08:01 917515 /lib/ld-2.14.1.so
bfa92000-bfab3000 rw-p 00000000 00:00 0 [stack]
ffffe000-fffff000 r-xp 00000000 00:00 0 [vdso]
```

Double Free Error in Eclipse (eclipse.org)



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```
*** glibc detected *** /home/lars/ZIB/workspace/test3/Release/test3:
free(): invalid pointer: 0x0804c01c ***
===== Backtrace: =====
/lib/libc.so.6(+0x6ff0b)[0xb74d7f0b]
/usr/lib/libstdc++.so.6(_ZdlPv+0x1f)[0xb76cfb2f]
/home/lars/ZIB/workspace/test3/Release/test3[0x8048cc8]
/home/lars/ZIB/workspace/test3/Release/test3[0x804891d]
/lib/libc.so.6(__libc_start_main+0xf3)[0xb7481003]
/home/lars/ZIB/workspace/test3/Release/test3[0x80489d1]
===== Memory map: =====
08048000-0804a000 r-xp 00000000 08:03 4068942    /home
/lars/ZIB/workspace/test3/Release/test3
```

Classes (user defined types)

can hold data

should reflect minimal independent sub-structures

```
class Point {  
public:  
    Point(double x_, double y_, double z_)  
        : x(x_), y(y_), z(z_)  
    {}  
  
    void reset() {  
        x = y = z = 0;  
    }  
  
private:  
    double x, y, z;  
};  
  
Point p(1.0, 1., 1.);  
p.reset();
```

// following code is visible to user

// constructor

// initialization

// member function

// hidden from user

// declaration

Classes (user defined types)

new keywords: default, delete

```
class Point {  
public:  
    Point() = default;           // following code is visible to user  
                                // use default default constructor  
  
    Point(Point const&) = delete; // no copy constructor  
    Point& operator=(Point const& /*other*/) = delete; // no copy by assignment  
  
    ...  
private:                        // hidden from user  
    double x,y,z;               // declaration  
};  
  
Point p(1.0,1.,1.);  
p.reset();  
Point q;                        // same as Point q(0.,0.,0.);
```

static member variables

not part of object, exist independently
do not have an address until declared outside the class

```
class Point {  
public:  
    static constexpr int dim = 3;  
    ...  
};  
  
static constexpr int Point::dim;  
  
std::cout << "dim: " << Point::dim << std::endl;
```

// following code is visible to user

// now Point::dim has an address

Inheritance

build hierarchies of classes that make sense independently

```
// Base class
class Shape {
public:
    void setWidth(double w) {
        width = w;
    }

    void setHeight(double h) {
        height = h;
    }

    double getHeight() const {
        return height;
    }

    double getWidth() const {
        return width;
    }

protected:
    double width;
    double height;
};
```

```
// Derived class
class Rectangle: public Shape {
public:
    Rectangle() = default;

    double getArea() {
        return (width * height);
    }
};

double computeBoundingBox(Shape const& shape) {
    return shape.getWidth()*shape.getHeight();
}

int main() {
    Rectangle rect = Rectangle();
    Shape shape0 = rect;           // shape is a shape
    Shape& shape = rect;           // shape is a rectangle
    shape.setWidth(1.0);
    shape.setHeight(1.0);
    double area =
        dynamic_cast<Rectangle>(shape).getArea();
}
```

Virtual inheritance

use (possibly abstract) base classes as interface

```
// Base class
class Shape {
public:
    void setWidth(double w) {
        width = w;
    }

    void setHeight(double h) {
        height = h;
    }

    double getHeight() const {
        return height;
    }

    double getWidth() const {
        return width;
    }

    virtual double getArea() const = 0;

protected:
    double width, height;
};
```

```
// Derived class
class Rectangle: public Shape {
public:
    Rectangle() = default;

    virtual double getArea() const {
        return (width * height);
    }
};

double computeBoundingBox(Shape const& shape){
    return shape.getWidth()*shape.getHeight();
}

int main() {
    Rectangle rect;
    Shape shape0 = rect;
    Shape& shape = rect;
    shape.setWidth(1.0);
    shape.setHeight(1.0);
    double area = shape.getArea();
}
```

no implementation
=> class Shape is abstract

Operators

- arithmetic operators, i.e. =, +, -, *, /, ...
- relational operators, i.e. ==, !=, >, <, ...
- logical operators, !, &&, ||
- pointer operators, *, &, ->
- function operator (), i.e. for functors (classes whose objects can be used as functions)
- ...

see https://en.wikipedia.org/wiki/Operators_in_C_and_C++ for an overview

Syntax for member operators (here for '*' and '=')

```
class Rectangle { ...  
    Rectangle& operator*=(double scaling) {  
        this->getWidth() *= scaling;  
        this->getHeight() *= scaling;  
        return *this;  
    }  
};
```

Operators

- arithmetic operators, i.e. =, +, -, *, /, ...
- relational operators, i.e. ==, !=, >, <, ...
- logical operators, !, &&, ||
- pointer operators, *, &, ->
- function operator (), i.e. for functors (classes whose objects can be used as functions)
- ...

see https://en.wikipedia.org/wiki/Operators_in_C_and_C++ for an overview

Syntax for free operators (here for '==')

```
void operator==(Rectangle const& rect1, Rectangle const& rect2)
{
    if( ( rect1.getHeight() != rect2.getHeight() ) ||
        ( rect1.getWidth()   != rect2.getWidth() ) ) return false;
    ... // more checks

    return true;
}
```

- same function name, different arguments
- typical use-case: overloading free operators such as `operator<<`, `operator<`, ...

overloading the stream operator `<<`

write `std::vector<int>` to console:

```
for(int e : vec) std::cout << e << " ";  
std::endl;
```

with overloading of `operator<<`:

```
std::ostream& operator<<(std::ostream& os,  
                        std::vector<int> const& vec)  
{  
    for(int e : vec) os << e << " ";  
    os << std::endl;  
    return os;  
}  
...  
std::cout << vec << std::endl;
```

Summary:

- same name, different arguments
- legal in C++ (not in C)
- compiler "mangles" arguments into name to make linker happy
i.e. `_ZlsRSoRKSt6vectorIiSaIEE`, `_ZlsRSoRKSt6vectorIdSaIEE`

```
std::ostream& operator<<(std::ostream& os,  
                        std::vector<int> const& vec);  
  
std::ostream& operator<<(std::ostream& os,  
                        std::vector<double> const& vec);
```

- can not overload for only built-in types
- do not overload in counterintuitive ways

- Division into *.cpp and *.hh files.
- Point class: Put declarations into point.hh file

```
#ifndef POINT_HH_
#define POINT_HH_

#include <array>

class Point
{
    public:
        Point(double x, double y, double z);
        // reset point to origin
        void reset();
        // access coordinates
        double& operator[](size_t coordinateIndex);
        // read-only access
        double const& operator[](size_t coordinateIndex) const;

    private:
        std::array<double,3> position;
};

#endif
```

// include guard: avoids
// multiple inclusion of
// header file

// visible to user
// constructor

// member function

function does not
change local
member variables

// hidden from user

// end include guard

- Division into *.cpp and *.hh files.
- Point class: Put declarations into point.cpp file

```
#include „point.hh“

Point::Point(double x, double y, double z) {
    position[0] = x;
    position[1] = y;
    position[2] = z;
}

Point::reset() { position.fill(0.0); }

double& Point::operator[](size_t coordinateIndex)
{
    return position[coordinateIndex];
}

double const& Point::operator[](size_t coordinateIndex) const
{
    return position[coordinateIndex];
}
```

Gerald Weinberg, computer scientist and author:

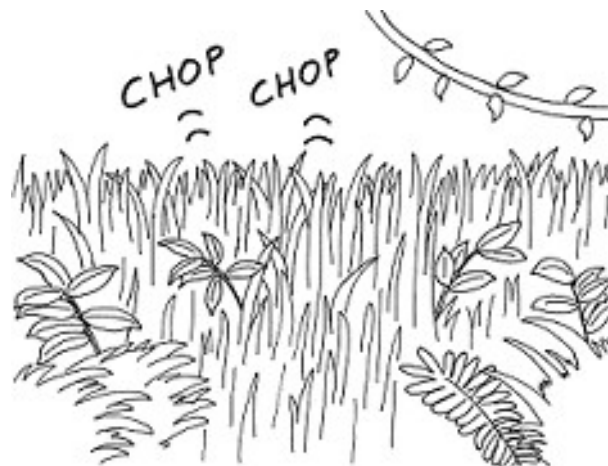
"If builders built buildings the way programmers write programs,
then the first woodpecker that came along would destroy civilization."

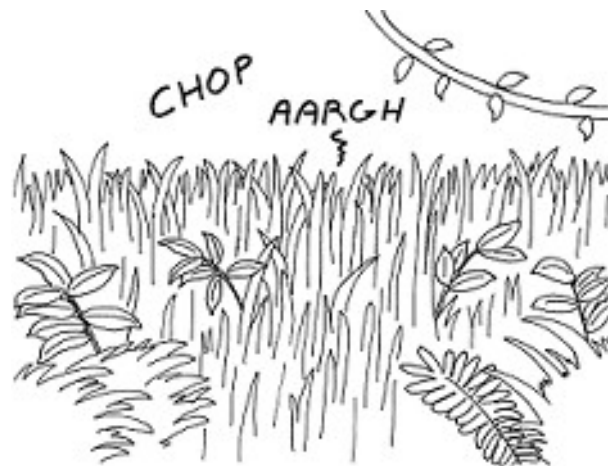
ağaçkakan



Robert C. Martin , „Clean Code: A Handbook of Agile Software Craftmanship“:

"Have you ever been significantly impeded by bad code? If you are a programmer of any experience then you've felt this impediment many times. [...]. We call it wading. We wade through bad code. We slog through a morass of tangled brambles and hidden pitfalls. We struggle our way, hoping for some hint, some clue, of what is going on; but all we see is more and more senseless code."







WHY IS THIS
STRUCTURE HERE ?



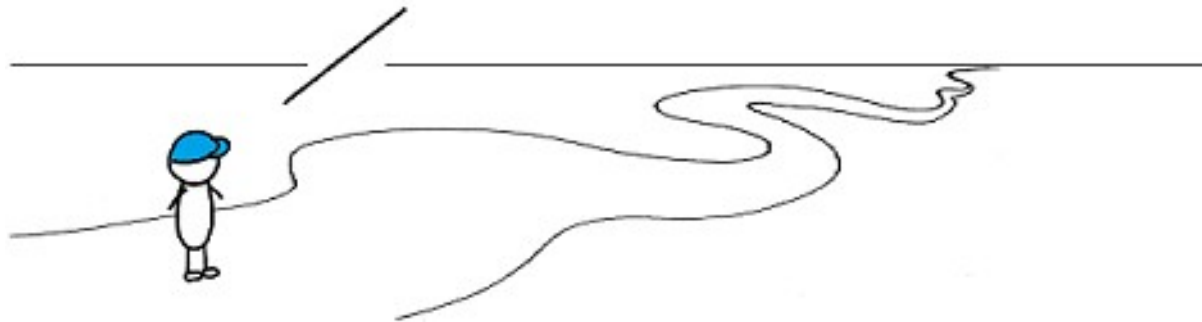
WHERE COULD THIS BRIDGE
POSSIBLY LEAD ?



THIS SIGN DOESN'T
HELP ME MUCH.



WHAT A HORRIBLY DESIGNED
STREET, MOST INEFFICIENT.



GOOD GOD! WHAT THE HELL
DOES THIS CONTRAPTION DO?



taken from abstrusegoose.com/432

Robert C. Martin , „Clean Code: A Handbook of Agile Software Craftmanship“:

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"Of course you have been impeded by bad code. So then

Robert C. Martin , „Clean Code: A Handbook of Agile Software Craftmanship“:

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"Of course you have been impeded by bad code. So then – **why did you write it?**"

Robert C. Martin , „Clean Code: A Handbook of Agile Software Craftmanship“:

"Were you trying to go fast? Were you in a rush? Probably so. Perhaps you felt that you didn't have time to do a good job; that your boss would be angry with you if you took the time to clean up your code. Perhaps you were just tired of working on this program and wanted it to be over. Or maybe you looked at the backlog of other stuff that you had promised to get done and realized that you needed to slam this module together so you could move on to the next. We've all done it."

Robert C. Martin , „Clean Code: A Handbook of Agile Software Craftmanship“:

"Were you trying to go fast? Were you in a rush? Probably so. Perhaps you felt that you didn't have time to do a good job; that your boss would be angry with you if you took the time to clean up your code. Perhaps you were just tired of working on this program and wanted it to be over. Or maybe you looked at the backlog of other stuff that you had promised to get done and realized that you needed to slam this module together so you could move on to the next. We've all done it."

"We've all looked at the mess we've just made and then have chosen to leave it for another day. We've all felt the relief of seeing our messy program work and deciding that a working mess is better than nothing. We've all said we'd go back and clean it up later."

Of course, in those days we didn't know LeBlanc's law: **LATER EQUALS NEVER.**"

Difficulties in programming

- 1) Implicit assumptions by the programmer that are not well documented
"One man's constant is another man's variable." (Alan Perlis)
- 2) Obscure variable, class and function names
- 3) Counterintuitive names, behaviour, ...
- 4) Unclear general library/program structure
- 5) (Premature) Optimization
- 6) ...

Necessary requirement for larger projects:
Coding Standards/Clean Code

Robert C. Martin , "Clean Code: A Handbook of Agile Software Craftmanship":

- "In software, 80% or more of what we do is quaintly called *maintenance*, the **act of repair.**"

Expressive Naming

- 1) expressive function, variable and class names
- 2) document only if information can not be expressed by 1)

```
/// Returns the sum of a0 and a1.  
double foo(double a0, double a1)  
{  
    return a0+a1;  
}  
  
// better  
  
double add(double x, double y) {  
    return x+y;  
}
```

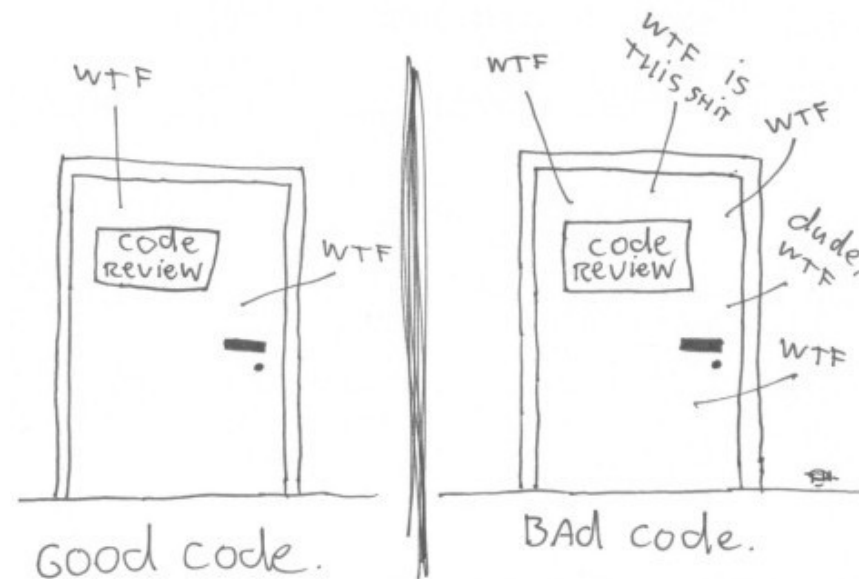
```
for(int i = 0; i<dim; ++i)
{
    if(container.vn[ vid[i] ].isRelevant)
    {
        m[i] = (tangs[evid[i]] * ne) / (tangs[evid[i]] * te);
        policy.apply(m[i]);
    }
    else m[i] = 0;
}
...
```

What is going on here?

```
for(int i = 0; i<dim; ++i)
{
    if(container.vn[ vid[i] ].isRelevant)
    {
        m[i] = (tangs[evid[i]] * ne) / (tangs[evid[i]] * te);
        policy.apply(m[i]);
    }
    else m[i] = 0;
}
...
```

```
/* * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * */
/* fill right hand side */
/* * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * */
// first determine the desired gradients and apply threshold
for(int vertexIdInEdge = 0; vertexIdInEdge<dim; ++vertexIdInEdge)
{
    if(container.vertexNormals[ globalEdgeVertexIds[vertexIdInEdge] ].isRelevant)
    {
        desiredGradients[vertexIdInEdge] =
            (tangents[localEdgeVertexIds[vertexIdInEdge]] * faceNormal) /
            (tangents[localEdgeVertexIds[vertexIdInEdge]] * edgeDirection);
        policy.applyGradientThreshold(desiredGradients[vertexIdInEdge]);
    }
    else desiredGradients[vertexIdInEdge] = 0;
}
...
```


The ONLY valid measurement
of code quality: WTFs/minute

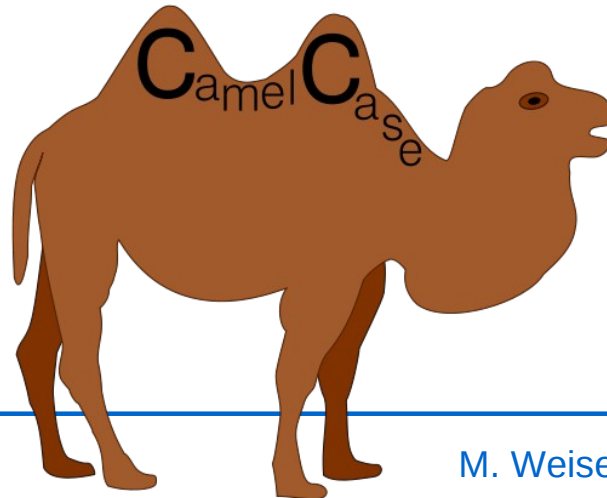


(c) 2008 Focus Shift/OSNews/Thom Holwerda - <http://www.osnews.com/comics>

Standardize syntax, i.e. for Kaskade7 this means

- 1) For type names we **always** use "UpperCamelCase",
i.e. "class VariableSetDescription".
- 2) For functions, objects, ... we **always** use "lowerCamelCase"
i.e. "VariableSetDescription variableSetDescription".
- 3) We **never** use tabs, instead we use whitespaces
(you can tell your editor to replace tabs with whitespaces).
- 4) Access on private member variables via get..., set...
i.e. access private member `int dim` of `class Point` via
`Point& setDim(int dim_);`
`int getDim() const;`
- 5) curly braces start on a new line (not rigorously done on the
slides because of lacking space)

6) ...



Donald Knuth, 1974:

"Programmers waste enormous amounts of time thinking about or worrying about, the speed of noncritical parts of their programs, and these attempts at efficiency actually have a strong impact when debugging and maintenance are considered. We should forget about small efficiencies, say about 97% of the time:

premature optimization is the root of all evil.

Yet we should not pass up our opportunities in that critical 3%."

- Think about overall structure and modularity. Professionally designed software does not require much optimization.
- If you have a clever idea, forget it. („Premature optimization is the root of all evil!“)
- Premature pessimization is not better,
i.e. if you pass a reference and are not sure about life time,
do not change this reference to a copy of your object,
instead think about how to guarantee adequate life time.
- Programming is about being scrupulous and honest, not about begin creative!
i. e. think about your code and **test it in different** situations.

What is more important, readability or performance?

- 1) performance matters, but
- 2) sub-optimal performance, good readability
=> code works and can be used by others
- 3) optimize only if it pays off
 - almost everything can be optimized for performance
 - in most cases this will save some milliseconds in a program that runs for some seconds/minutes (=> do not optimize)

"The most impressive performance increase is the not-working to working transition."

- John Ousterhout -

1. Compile cleanly at high warning levels.
3. Use a version control system (svn, git, ...)
4. Invest in code reviews.
5. Give one entity one cohesive responsibility.
- 6. Correctness, simplicity, and clarity come first.**

- "The most important single aspect of software development is to be clear about what you are trying to build."

68. Assert liberally to document internal assumptions and invariants ...

C++

- www.cppreference.com
- Herb Sutter: www.gotw.ca
 - "Exceptional C++"
 - "More Exceptional C++"
- Alexei Alexandrescu : "Modern C++ Design"
- <http://www.drdobbs.com/cpp>
- C++ In-Depth Series

Coding Standards/Clean Code

- Herb Sutter, Andrei Alexandrescu, "C++ Coding Standards"
- Robert C. Martin, "Clean Code: A Handbook of Agile Software Craftmanship"

Alan Perlis, computer scientist

„Get into a rut early: Do the same process the same way. Accumulate idioms.
Standardize. The only difference between Shakespeare and you was the size of his idiom list – not the size of his vocabulary.“

„Fools ignore complexity. Pragmatists suffer it. Some can avoid it.
Geniuses remove it.“

Standard Library

containers, algorithms and IO

"Just because the standard provides a cliff in front of you,
you are not necessarily required to jump off it."

Norman Diamond

std::array

fixed size array (no insertion or removal of elements)
constant time random access

```
std::array<int,3> = { 1, 2, 3 };
```

std::list

insertion & removal of elements in constant time
linear complexity for accessing elements (slow!)

std::map

sorted, associative container
search, insertion, removal in logarithmic complexity

```
std::map<std::string,char> gradeList;  
gradeList["Martin"] = 'A';  
gradeList["Lars"] = 'A';
```

std::vector

„dynamic“ array

constant time random access

insertion and removal of elements in linear complexity wrt. distance to the end

```
std::vector<double> v0 = { 1.1, 2.2, 3.3 };
```

```
std::vector<int> v1(20);
```

```
std::vector<int> v2,v3;
```

```
v2.resize(20);
```

```
for(int i=0; i<20; ++i)
```

```
{
```

```
    v1[i] = v2[i] = i;
```

```
    v3.push_back(i);
```

```
}
```

// most inefficient, allocate storage + store value

"By default, use **vector** when you need a container"

(Bjarne Stroustrup, developer of C++)

more about stl-containers: www.cppreference.com or any C++-book

- operate on stl-containers and stl-compliant containers, i.e. containers that provide iterators to access data, provide first-class or move-semantics
- provide widely used basic functionalities

`std::max, std::min`

```
int a=3, b=4;  
int c = std::max(a,b)
```

`// c = 4`

`std::max_element, std::min_element`

```
std::vector<int> vec = { 1, 2, 3 };  
int a = *std::min_element(vec.begin(), vec.end());  
int b = *std::max_element(vec.begin(), vec.begin()+2);
```

`// a = 1`

`// b = 2`

`std::for_each`

apply function to range

```
void modifyIf22(double& d)
{
    if(d == 2.2) d = -1;
}

std::vector<double> vec = { 1.1, 2.2, 3.3 };
std::for_each(vec.begin(), vec.end(), &modifyIf22);
```

same with lambda-expression

```
std::for_each(vec.begin(), vec.end(),
    [](double& d)
    {
        if(d==2.2) d=-1;
    }
);
```

more algorithms

- find/find_if/find_if_not
- find_first_of
- all_of/none_of/any_of
- copy/copy_if
- transform
- swap
- unique
- sort
- lower_bound/upper_bound
- accumulate
- ...

STL-algorithms are

- **FAST**
- **VERIFIED**
- **WIDELY KNOWN**

more about stl-algorithms: www.cppreference.com

general idea: first write to stream-objects, then print to display/file

- `std::cout` // write to terminal
- `std::ofstream, std::iostream` // write to file
- `std::istream, std::iostream` // read from file

`std::cout`

global object

```
std::cout << "Nice to be in Ankara." << std::endl;
```

`std::ofstream`

```
std::ofstream os("filename");  
os << "Some data: " << " and more data" << std::endl;  
...  
os.close(); // write file
```

more about stl-input/output: www.cppreference.com

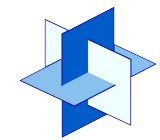
std::istream

```
std::istream file(„filename“);  
if(file.good())  
{  
    char line[1000];  
    while(!file.eof())  
    {  
        file.getline(line,1000);  
        ...  
    }  
}
```

// if file has been opened successfully

// while not at end of file do ...

// read up to 1000 characters of line



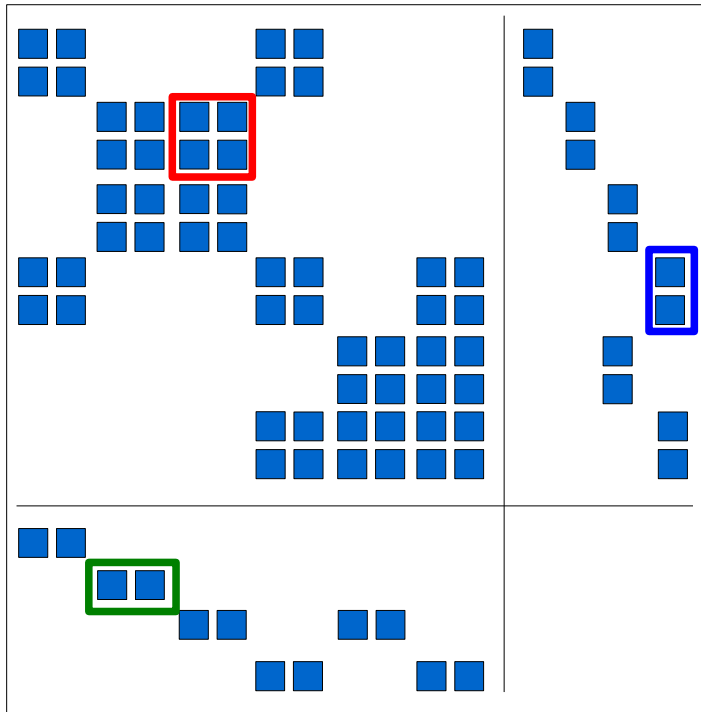
MATHEON



Template Metaprogramming

Stokes problem

$$\begin{aligned} -\Delta u + \nabla p &= f \\ \operatorname{div} u &= 0 \end{aligned}$$







sparsity structure of stiffness matrix

- heterogeneous block structure
(**dx****d**, **1x****d**, **dx****1**)
- different possibilities of organizing storage
- either explicitly stored and checked metainformation or implicit assumptions throughout the code

Storing FE coefficient vectors

- u and p live on different grid entities → no interleaving
[[u],[p]]
- components of u have physical meaning in every point → grouping
[[[u_{11},u_{12}],[u_{21},u_{22}],[u_{31},u_{32}],...],[p_1,p_2,p_3 ,...]]
- structured representation in `std::vector`'s is highly inefficient (and loses structure)

```
vector<vector<vector<double>>,vector<vector<double>>>>
```

u  p  components
  variable's values

- 'flat' representation contains no structure

```
vector<double>
```

Type safety and structured data

Compilers are much better at tedious error checking than programmers.

- array access checking
- array blocking

Aggressive compiler optimizations

Compilers are much better at **low level** optimizations than programmers.

- loop unrolling
- inlining
- constant folding
- dead code elimination

Code transformations

Computers (e.g. compilers) are much better at repetitive tasks than programmers.

- expression templates

A Template Metaprogram



MATHEON



```
template <int p, int i> struct isPrime {
    static int const value = (p==2) || (p%i) && isPrime<p,i-1>::value;
};
template <int p> struct isPrime<p,1> {
    static int const value = true;
};

template <int p> struct previous {
    static int const value = isPrime<p-1,p-2>::value? p-1:
                                                                    previous<p-1>::value;
};
template <> struct previous<2> {
    static int const value = 1;
};

template <int p> struct is {
    static int const value = is<previous<p>::value>::value;
};
template <> struct is<1> {};

int main() { return is<23>::value; } // what does main() return?
```

[Unruh '95]

A Template Metaprogram

```
$ g++ prime.cpp
prime.cpp: In function 'int main()':
prime.cpp:17: instantiated from 'const int is<2>::value'
prime.cpp:17: instantiated from 'const int is<3>::value'
prime.cpp:17: instantiated from 'const int is<5>::value'
prime.cpp:17: instantiated from 'const int is<7>::value'
prime.cpp:17: instantiated from 'const int is<11>::value'
prime.cpp:17: instantiated from 'const int is<13>::value'
prime.cpp:17: instantiated from 'const int is<17>::value'
prime.cpp:17: instantiated from 'const int is<19>::value'
prime.cpp:17: instantiated from 'const int is<23>::value'
prime.cpp:21: instantiated from here
prime.cpp:17: error: 'value' is no element of 'is<1>'
```

[GCC 4.0.2]



C++ templates form a complete Turing machine,
executing (weird) code at compile time.

FE coefficient vectors

Stokes: [[[u11,u12],[u21,u22],[u31,u32],...], [p1,p2,p3,...]]

Fixed-size vectors

```
template <class Scalar, int n>
class FieldVector {
    Scalar data[n];
public:
    Scalar& operator[](int i) { return data[i]; }
    void operator+=(FieldVector& v) {
        for (int i=0; i<n; ++i) data[i] += v[i]; // loop unrolling
    }
};
```

```
[ std::vector<FieldVector<double,n>>, std::vector<double> ]
```

- compiler knows and enforces that all u's have the same number of components
- coefficients of u and p are contiguous in memory
- different type of coefficient array for each variable

```
template <class T0, class T1 /* maybe more */>
struct HeterogeneousVector {
    T0 data0; // for u: T0 = std::vector<FieldVector<double,2>>
    T1 data1; // for p: T1 = std::vector<FieldVector<double,1>>
    // maybe more
};

// access by index
template <class T0, class T1, int n>
struct VectorAccess {};

template <class T0, class T1>
struct VectorAccess<T0,T1,1> { // partial specialization n=1
    typedef T1 type;
    type& at(HeterogeneousVector<T1,T2>& v) { return v.data1; }
};

template <class T1, class T2, int n>
VectorAccess<T1,T2,n>::type& at(HeterogeneousVector<T1,T2>& v) {
    return VectorAccess<T1,T2,n>::at(v);
}
```




```
boost::fusion::vector<T1, T2>
```

... and a lot more!

Element access

```
using namespace boost::fusion;  
  
vector<std::string, double> v;  
at_c<0>(v) = "pi";  
at_c<1>(v) = 3.1415;
```



data structures become

- general
- structure preserving
- type-safe
- efficient
- ugly

Loop Unrolling

```
double dynamic_sum(double* x,  
                   int n) {  
    double sum = 0;  
    for (int i=0; i<n; ++i)  
        sum += x[i];  
    return sum;  
}
```

...

```
double data[3];  
sum = dynamic_sum(data,3);
```

```
template <int n>  
double static_sum(double* x) {  
    double sum = 0;  
    for (int i=0; i<n; ++i)  
        sum += x[i];  
    return sum;  
}
```

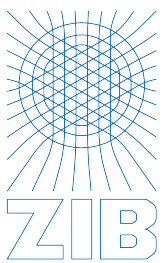
...

```
double data[3];  
sum = static_sum<3>(data);
```

Loop Unrolling



MATHEON



```
.LFB508:
    pushl    %ebp
.LCFI0:
    movl     %esp, %ebp
.LCFI1:
    movl     12(%ebp), %edx
    movl     8(%ebp), %ecx
    testl    %edx, %edx
    jle      .L9
    fldz
    xorl     %eax, %eax
    .p2align 4,,7
.L5:
    faddl    (%ecx,%eax,8)
    addl     $1, %eax
    cmpl     %edx, %eax
    jne      .L5
    popl     %ebp
    ret
.L9:
    popl     %ebp
    fldz
    ret
```

```
.LFB513:
    pushl    %ebp
.LCFI2:
    movl     %esp, %ebp
.LCFI3:
    movl     8(%ebp), %eax
    fldz
    popl     %ebp
    faddl    (%eax)
    faddl    8(%eax)
    faddl    16(%eax)
    ret
```

[g++ -O3 -S]



code becomes

- more compact
- faster

```
struct Integrand {
    virtual double f(double x)=0;
};

struct Constant: public Integrand {
    virtual double f(double x) {
        return 1; }
};

double integral(Integrand& f,
                int n) {
    double sum = 0;

    for (int i=0; i<n; ++i)
        sum += f.f((i+0.5)/n);

    return sum/n;
}

...
Constant f;
integral(f,1000000000);
```

```
struct Constant {
    double f(double x) {
        return 1; }
};

template <class Integrand>
double Integral(Integrand& f,
                int n) {
    double sum = 0;

    for (int i=0; i<n; ++i)
        sum += f.f((i+0.5)/n);

    return sum/n;
}

...
Constant f;
integral(f,1000000000);
```

```

_ZN8ConstantClEd:
.LFB2:
    movsd .LC0(%rip), %xmm0
    ret

main:
.LFB4:
    pushq %rbp
.LCFI4:
    pushq %rbx
.LCFI5:
    movl $1, %ebx
    subq $40, %rsp
.LCFI6:
    leaq 16(%rsp), %rbp
    movq $_ZTV8Constant+16, 16(%rsp)
    movsd .LC3(%rip), %xmm0
    movq %rbp, %rdi
    call *_ZTV8Constant+16(%rip)
    movapd %xmm0, %xmm1
    addsd .LC1(%rip), %xmm1
    .p2align 4,,7
.L13:
    cvtsi2sd %ebx, %xmm0
    movq 16(%rsp), %rax
    movsd %xmm1, (%rsp)
    movq %rbp, %rdi
    addl $1, %ebx
    addsd .LC2(%rip), %xmm0
    divsd .LC4(%rip), %xmm0
    call *(%rax)
    movsd (%rsp), %xmm1
    cmpl $1000000000, %ebx
    addsd %xmm0, %xmm1
    jne .L13
    divsd .LC4(%rip), %xmm1
    addq $40, %rsp
    popq %rbx
    popq %rbp
    cvtsd2si %xmm1, %eax
    ret
    
```

```

main:
.LFB4:
    movsd .LC0(%rip), %xmm0
    movl $1, %eax
    movapd %xmm0, %xmm1
    .p2align 4,,7
.L2:
    addl $1, %eax
    addsd %xmm1, %xmm0
    cmpl $1000000000, %eax
    jne .L2
    divsd .LC1(%rip), %xmm0
    cvtsd2si %xmm0, %eax
    ret
    
```

[g++ -O3 -S]

Timings

dynamic	11.85s
static	1.48s

Template Metaprogramming Impact



MATHEON



- ✓ compact code
- ✓ general code
- ✓ type safety
- ✓ performance

- ✗ long compile times
- ✗ strange syntax

- ✓ compact code
- ✓ general code
- ✓ type safety
- ✓ performance



- ✗ long compile times
- ✗ strange syntax

Example: tiny matrices

```
template <class T, int rows, int cols>
class Matrix {
public:
    T const& operator(int r, int c) const;
};

template <class T, int n, int k, int m>
Matrix<T,n,m> operator*(Matrix<T,n,k> const& A,
                        Matrix<T,k,m> const& B) {
    Matrix<T,n,m> AB(0);
    for (int i=0; i<n; ++i)
        for (int j=0; j<m; ++j)
            for (int l=0; l<k; ++l)
                AB(i,j) += A(i,l)*B(l,j);
    return AB;
}
```

- one piece of code works for many situations
- "debug once, run everywhere"

- ✓ compact code
- ✓ general code
- ✓ type safety
- ✓ performance



Example: tiny matrices

```
Matrix<double,2,3> A, B;  
Matrix<double,3,3> AB = A*B; // compile time error  
Matrix <complex<double>,3,2> C;  
Matrix <double,3,3> CA = C*A; // compile time error
```

- ✗ long compile times
- ✗ strange syntax

- less need to debug programs during runtime
(in fact, we rarely do)
- more need to digest cryptic compiler error messages

Rule of thumb: When the compiler accepts the code, it is semantically correct.

- ✓ compact code
- ✓ general code
- ✓ type safety
- ✓ performance



- ✗ long compile times
- ✗ strange syntax

Example: tiny matrices

```
template <class T, int rows, int cols>
```

```
Matrix<double,2,2> A, B;
```

```
Matrix<double,2,2> AB = A*B;
```

```
// equivalent to
```

```
AB(0,0) = A(0,0)*B(0,0) + A(0,1)*B(1,0);
```

```
AB(0,1) = A(0,0)*B(0,1) + A(0,1)*B(1,1);
```

```
AB(1,0) = A(1,0)*B(0,0) + A(1,1)*B(1,0);
```

```
AB(1,1) = A(1,0)*B(0,1) + A(1,1)*B(1,1);
```

- inlining
- loop unrolling
- dead code elimination