

Approximation Algorithms (ADM III)

4- Deterministic Rounding of Linear Programs

Guillaume Sagnol



Outline

- 1** Minimizing Sum of Completion Times on a Single Machine
- 2 Minimizing Weighted Sum of Completion Times
- 3 Prize-Collecting Steiner Tree Problem
- 4 Uncapacitated Facility Location Problem
- 5 Bin Packing Revisited

The scheduling problem $1|r_j|\sum_j C_j$

Given: jobs with processing time $p_j > 0$, release date $r_j \geq 0, j = 1, \dots, n$.

Task: Schedule the jobs nonpreemptively on a single machine;

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Proof: Use an exchange argument. □

Converting Preemptive into Nonpreemptive Schedule

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For each job $j = 1, \dots, n$, it holds that $C_j \leq 2 \cdot C_j^P$.

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Lemma 4.4

The completion times C_j of a feasible schedule satisfy the LP constraints.

Scheduling in Order of LP Completion Times

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Despite the exponential number of constraints, an optimal solution C^* to the LP relaxation can be computed in polynomial time.

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The algorithm above is a 3-approximation algorithm.

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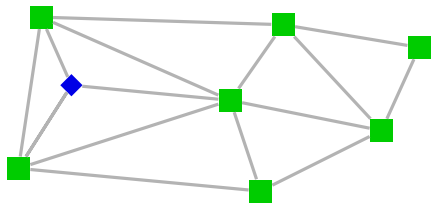
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Example:



◆ Root node

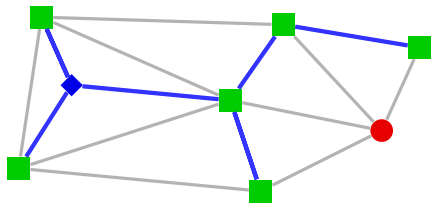
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Example:



- ◆ Root node
- Connected Terminal
- Disconnected Terminal

$$\text{COST} = c(\text{ — }) + \pi(\text{ ● })$$

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IP formulation:

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LP relaxation: $x_e \geq 0$ for all $e \in E$ and $y_i \leq 1$ for all $i \in V$.

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Lemma 4.7

There is a primal-dual algorithm that returns a Steiner tree T on terminals U with cost at most $\frac{2}{\alpha} \sum_{e \in E} c_e \cdot x_e^*$.

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Theorem 4.8

For $\alpha = 2/3$ the cost of the solution returned by the algorithm is

$$c(E(T)) + \pi(V \setminus V(T)) \leq \frac{2}{\alpha} \sum_{e \in E} c_e \cdot x_e^* + \frac{1}{1-\alpha} \sum_{i \in V} \pi_i \cdot (1 - y_i^*) \leq 3 \cdot \text{OPT} .$$

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- client j might contribute w_{ij} to facility i for being connected to i .

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Lemma 4.10

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- $N^2(j) := \{\ell \in D \mid \text{client } \ell \text{ neighbors some facility } i \in N(j)\}$.

Lemma 4.9

If clients j_1, \dots, j_k have disjoint neighborhoods $N(j_1), \dots, N(j_k)$, then opening cheapest facility in each neighborhood costs $\leq \sum_{i \in F} f_i \cdot y_i^* \leq \text{OPT}$.

Lemma 4.10

For each client j , $v_j^* \geq c_{ij}$ for all $i \in N(j)$.

Proofs: ...



Deterministic LP Rounding Algorithm

- 1 compute optimal LP solutions (x^*, y^*) and (v^*, w^*) ;
- 2 while $D \neq \emptyset$
- 3 choose $j := \operatorname{argmin}_{j' \in D} v_{j'}^*$ and $i := \operatorname{argmin}_{i' \in N(j)} f_{i'}$;
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Proof:...



We finally mention the following non-approximability result without proof.

Theorem 4.12

There is no α -approximation algorithm for the metric uncapacitated facility location problem with $\alpha < 1.463$ unless each problem in NP has an $O(n^{O(\log \log n)})$ time algorithm.

Outline

- 1 Minimizing Sum of Completion Times on a Single Machine
- 2 Minimizing Weighted Sum of Completion Times
- 3 Prize-Collecting Steiner Tree Problem
- 4 Uncapacitated Facility Location Problem
- 5 Bin Packing Revisited**

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In the previous chapter we showed how to find a solution to instance I with at most $(1 + \varepsilon)\text{OPT}(I) + 1$ bins in polynomial time.

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Ingredients:

- Replace dynamic program with integer program plus LP rounding.
- Improved grouping scheme.
- Recursive application of two previous ingredients.

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Ingredients:

- Replace dynamic program with integer program plus LP rounding.
- Improved grouping scheme.
- Recursive application of two previous ingredients.

Notice:

By Lemma 3.14 we can assume that all items have size at least $1/\text{SIZE}(I)$.

Configuration Integer Program for Bin Packing

- let $s_1 > s_2 > \dots > s_m$ denote the different item sizes;
- for $i = 1, \dots, m$, let b_i denote the number of items of size s_i ;

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Configuration LP and its Dual

Primal:

$$\min \sum_{j=1}^N x_j$$
$$\text{s.t. } \sum_{j=1}^N t_{ij} \cdot x_j \geq b_i \quad \text{for all } i = 1, \dots, m,$$
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Notice: $\text{SIZE}(I) \leq \text{OPT}_{LP}(I) \leq \text{OPT}(I)$

Solving the Configuration LP Approximately

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An LP solution of value at most $\text{OPT}_{LP}(I) + 1$ can be computed in polynomial time.

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with $\delta_j \in \{1, 1 + \varepsilon\}$ and $|\{j \mid \delta_j = 1\}|$ polynomially bounded.

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Since $y^*/(1 + \varepsilon)$ is feasible dual solution, $\sum_{i=1}^m b_i \cdot y_i^* \leq (1 + \varepsilon)\text{OPT}_{LP}$.

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Moreover, for $J := \{j \mid \delta_j = 1\}$, vector y^* is optimal solution to

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Proof of Theorem 4.13 (Cont.)

Consider the corresponding

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\bar{y} is feasible solution to original primal LP of value at most $\text{OPT}_{LP} + 1$. \square

Harmonic Grouping Scheme and Rounding

Grouping

- consider items in order of non-increasing size;
- open a group and start putting items in current group, one at a time;
- close current group if its total size is at least 2 and start new group;

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Notice that $r \leq \lceil \text{SIZE}(I)/2 \rceil$ and $n_i \geq n_{i-1}$, for $i = 2, \dots, r - 1$.

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Rounding: Construct new instance I' as follows:

- discard items in G_1 and G_r ;
- for $i = 2, \dots, r - 1$ discard the $n_i - n_{i-1}$ smallest items in G_i ;
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Lemma 4.14

There are at most $\text{SIZE}(I)/2$ distinct item sizes in I' ; the total size of all discarded items is $O(\log \text{SIZE}(I))$. □

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BinPack(I)

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- 7 pack I_2 recursively via $\text{BinPack}(I_2)$;

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Lemma 4.15

$$\text{OPT}_{LP}(I_1) + \text{OPT}_{LP}(I_2) \leq \text{OPT}_{LP}(I') \leq \text{OPT}_{LP}(I).$$

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Theorem 4.16 (Karmarkar & Karp, 1982)

Algorithm BinPack runs in polynomial time and finds a solution using at most $\text{OPT}(I) + O(\log^2 \text{OPT}(I))$ bins.

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Theorem 4.17 (Hoberg & Rothvoß, 2015)

A solution using at most $\text{OPT}(I) + O(\log \text{OPT}(I))$ bins can be found in polynomial time.

